



# Eurographics 2015

The 36<sup>th</sup> Annual Conference of the  
European Association for Computer Graphics

## Composition-Aware Scene Optimization for Product Images

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# Motivation

35% of scenes in IKEA catalogue are CGI.



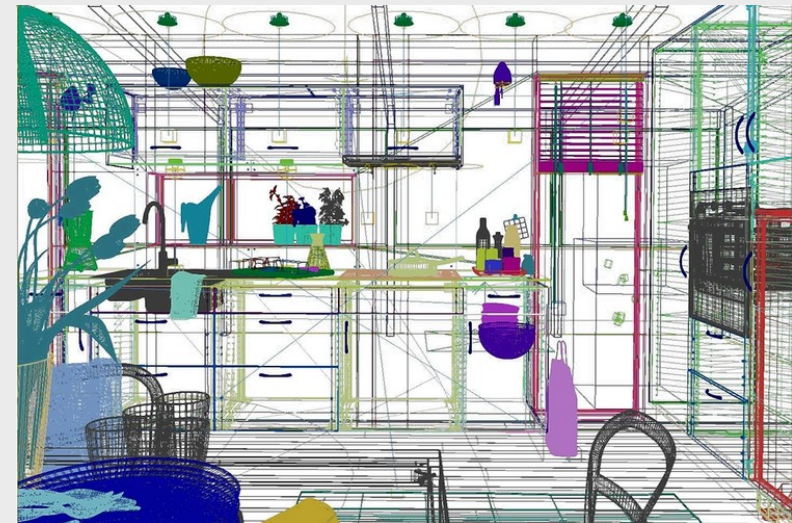
# Advantages

- Much less expensive
- Much easier for customization



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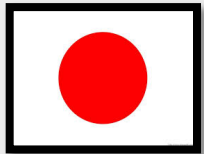
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# Artist's goal





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Input: a rough scene, objects to highlight, and an initial camera view



Rough layout



# Artist's goal

Input: a rough scene, objects to highlight, and an initial camera view



Highlight this chair  
and this table

# Artist's goal

Input: a rough scene, objects to highlight, and an initial camera view

Camera view



# Artist's goal

Output: a scene with optimized *object placement*, *materials* and *camera view* that produce an appealing 2D composition.



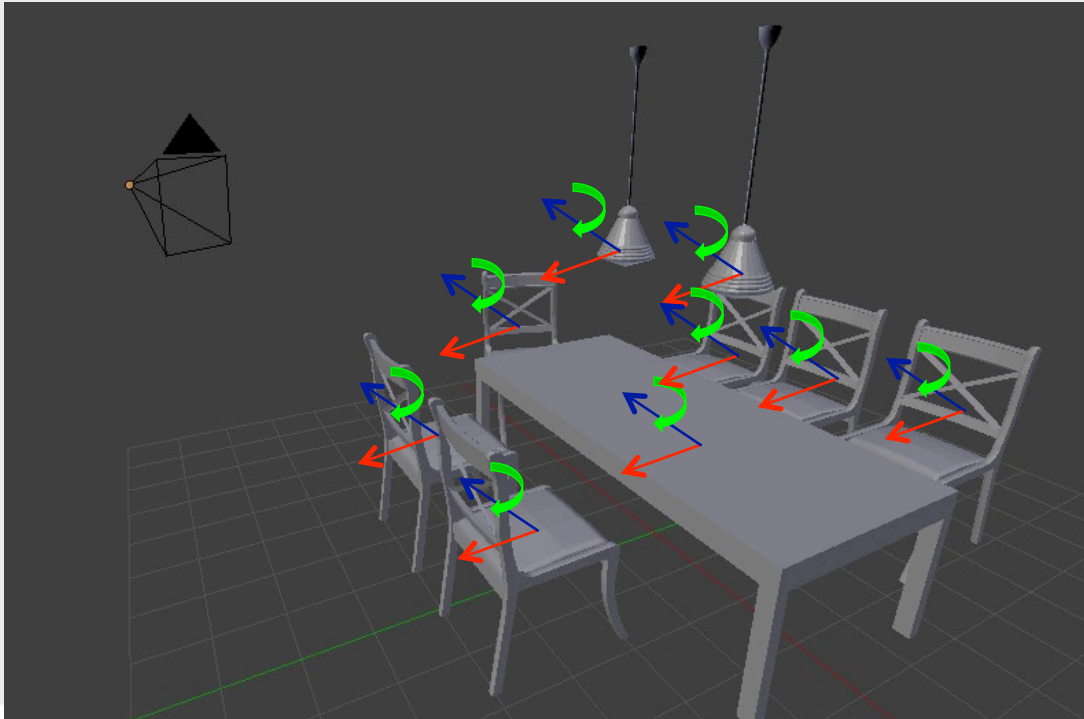
# Challenges

- Huge search space to explore
- Many principles/constraints to balance
- Requiring repeating work for customization



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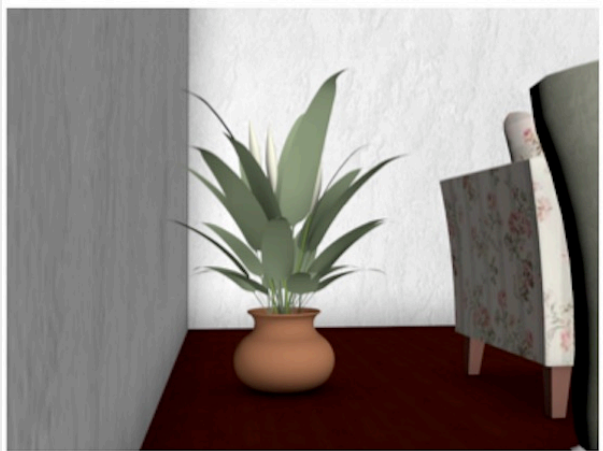


$4 * N + 6$  parameters

- 3 DOF per object
- 1 material per object
- 6 DOF for camera

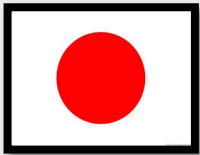
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# Previous Work

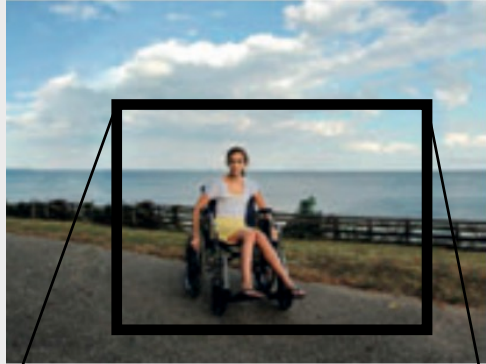
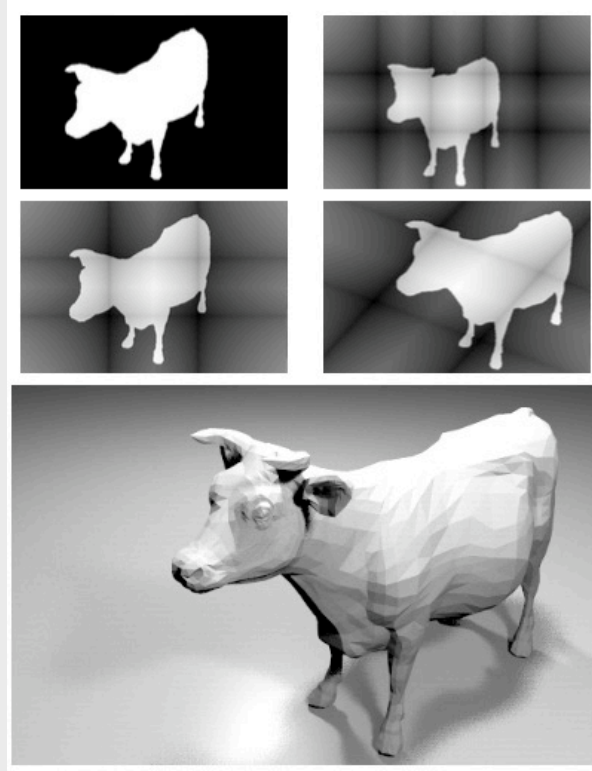


Image optimization  
[Liu et al. 2010]



Camera optimization  
[Gooch et al. 2001]



Scene optimization  
[Yu et al. 2011]

# Key Idea

$$E(\{x_i, y_i, \theta_i\}, \{m_i\}, C) = E_{op} + E_{os} + E_{ic} + E_{cp} + E_{3d} + E_r$$

$x_i, y_i$  : position of object  $i$  on its supporting surface



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$E_{op}, E_{os}, E_{ic}, E_{cp}, E_{3d}, E_r$  : terms for composition rules



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$$E(\{x_i, y_i, \theta_i\}, \{m_i\}, C) = E_{op} + E_{os} + E_{ic} + E_{cp} + E_{3d} + E_r$$

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$C$  : camera parameters **Never been considered before**

$E_{op}, E_{os}, E_{ic}, E_{cp}, E_{3d}, E_r$  : terms for composition rules



# Overview

- • Composition rules and constraints
- Optimization
- Applications





# Terms for composition rules and constraints

1. Object placement within 2D frame  $E_{op}$
2. Object saliency within the 2D frame  $E_{os}$
3. Image composition  $E_{ic}$
4. Camera placement  $E_{cp}$
5. Object constraints within the 3D scene  $E_{3d}$
6. Regularization  $E_r$



# Term 1: Object placement within 2D frame

- Rule of thirds
- Centeredness
- Clearance



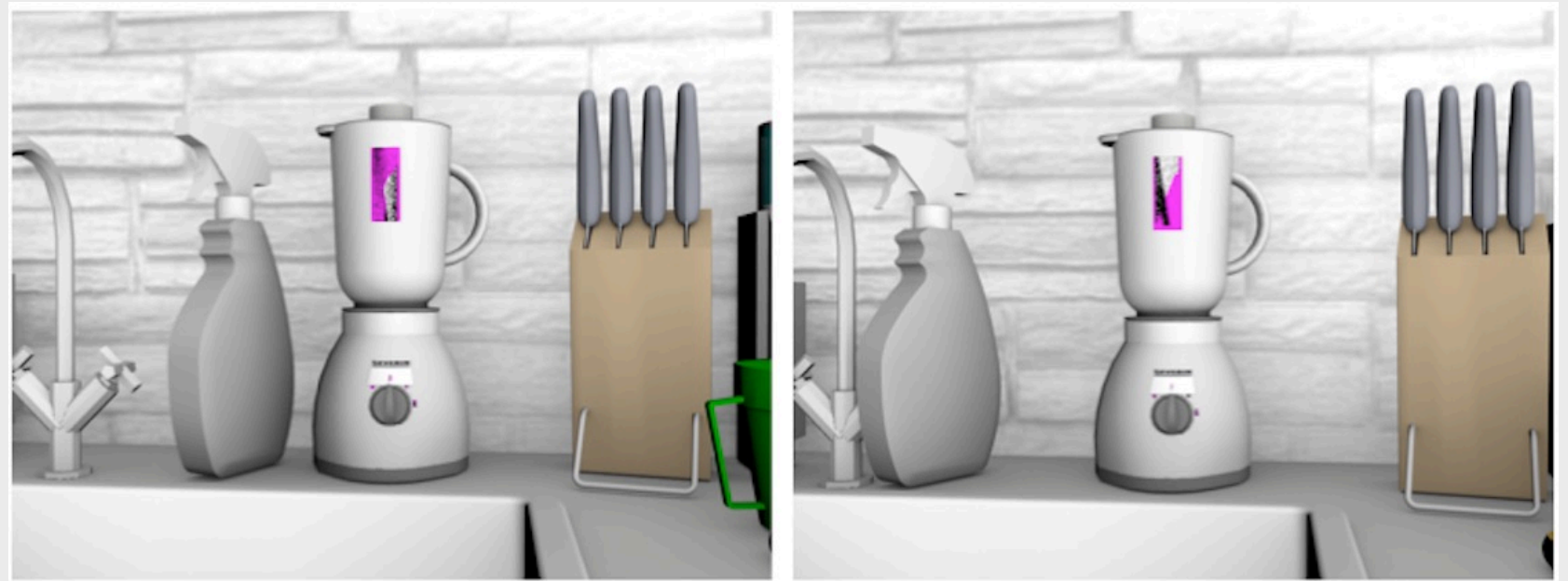
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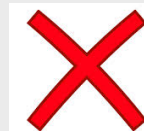
# Term 2: Object saliency within the 2D frame

- Visibility
- Object size



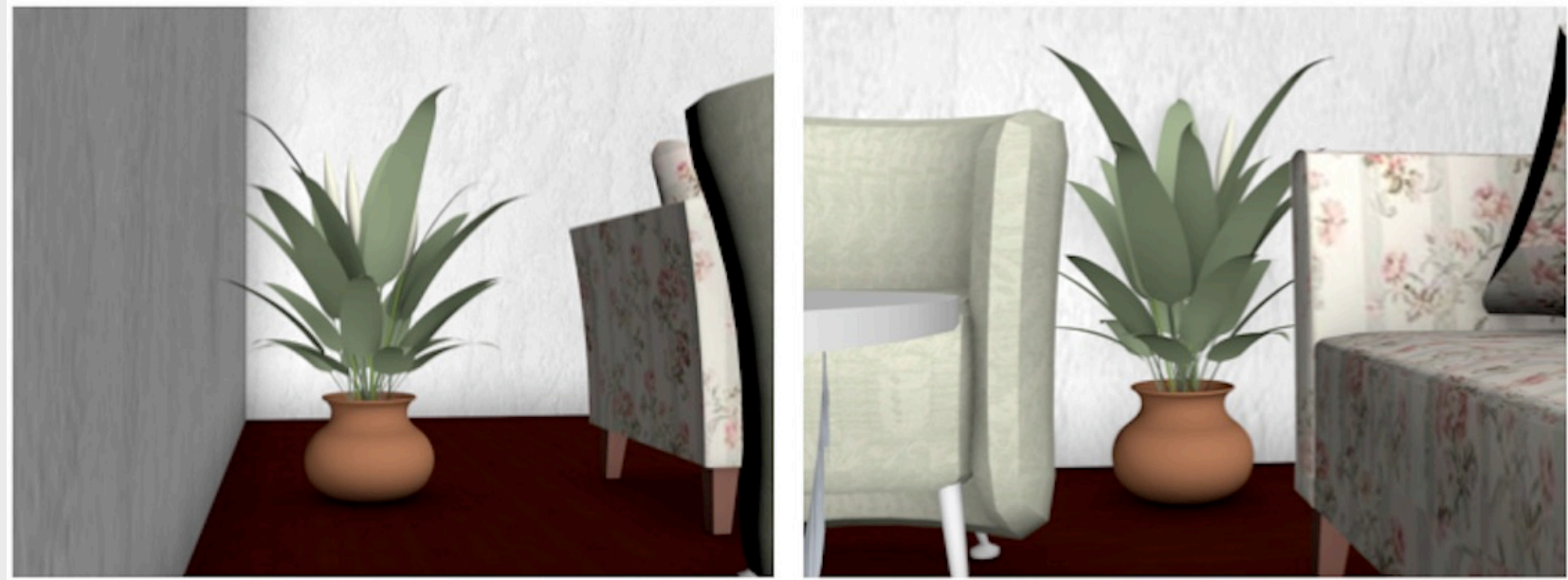
# Term 2: Object saliency within the 2D frame

- Visibility
- Object size



# Term 3: Image composition

- Visual balance
- Color contrast



# Term 3: Image composition

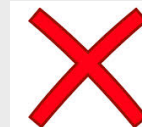
- Visual balance
- Color contrast





# Term 4: Camera placement

- Canonical views
- Typical views



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# Term 5: Object constraints within the 3D scene

- Collision relationships
- Support relationships
- Semantic constraints



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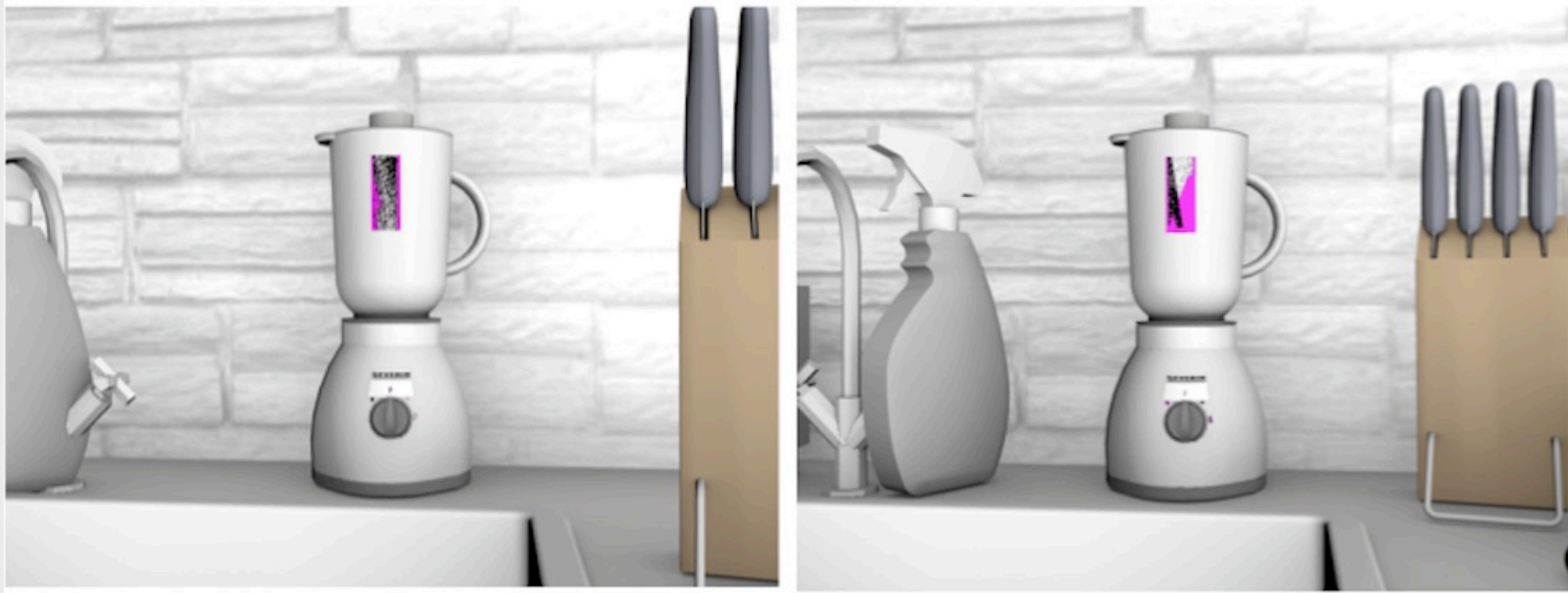


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- Collision relationships
- Support relationships
- Semantic constraints



# Term 6: Regularization



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→ • Optimization

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# Energy function

$$E(\{x_i, y_i, \theta_i\}, \{m_i\}, C) = E_{op} + E_{os} + E_{ic} + E_{cp} + E_{3d} + E_r$$

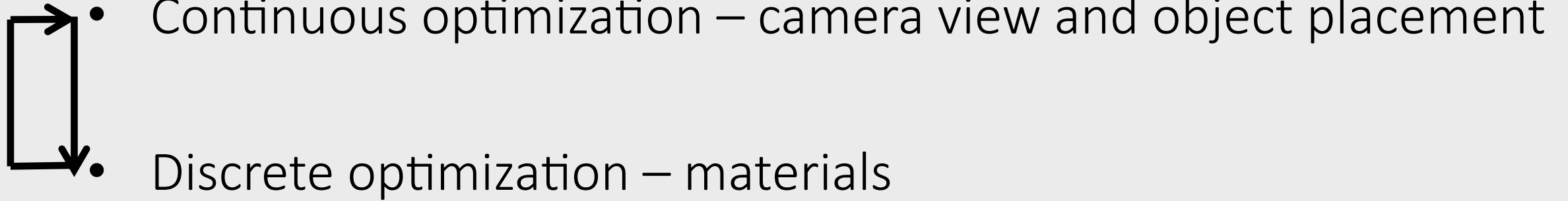
Continuous variables

Discrete variables





# Optimization

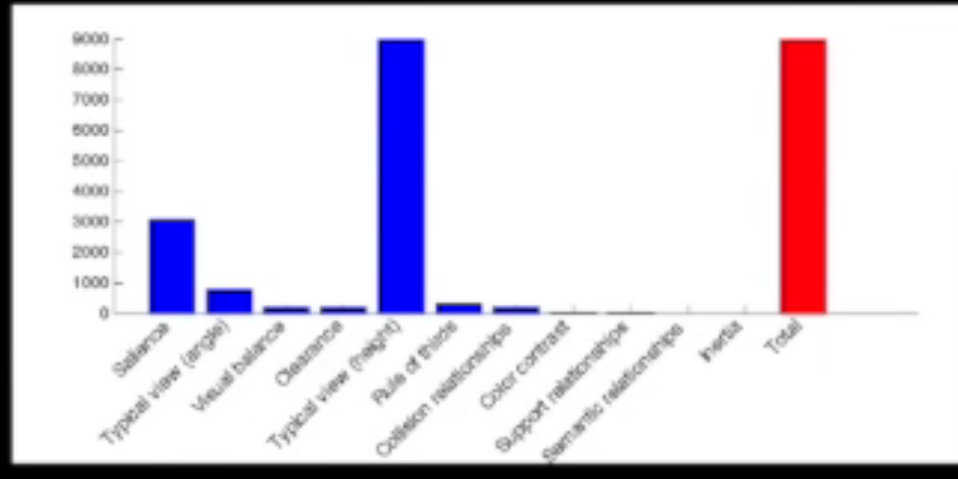
- 
- Continuous optimization – camera view and object placement
  - Discrete optimization – materials



# Example 1



Focus objects:  
Dining table, chair



# Overview

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# Applications

1. Refining rough compositions
2. Retargeting for different aspect ratios
3. Retargeting for different cultural preferences
4. Text-incorporated composition
5. Generating detail images from an overview



# Application 1: Refining rough compositions



Rough composition



Optimized composition

# Application 1: Refining rough compositions

## User study



# Application 1: Refining rough compositions

User study

Reference

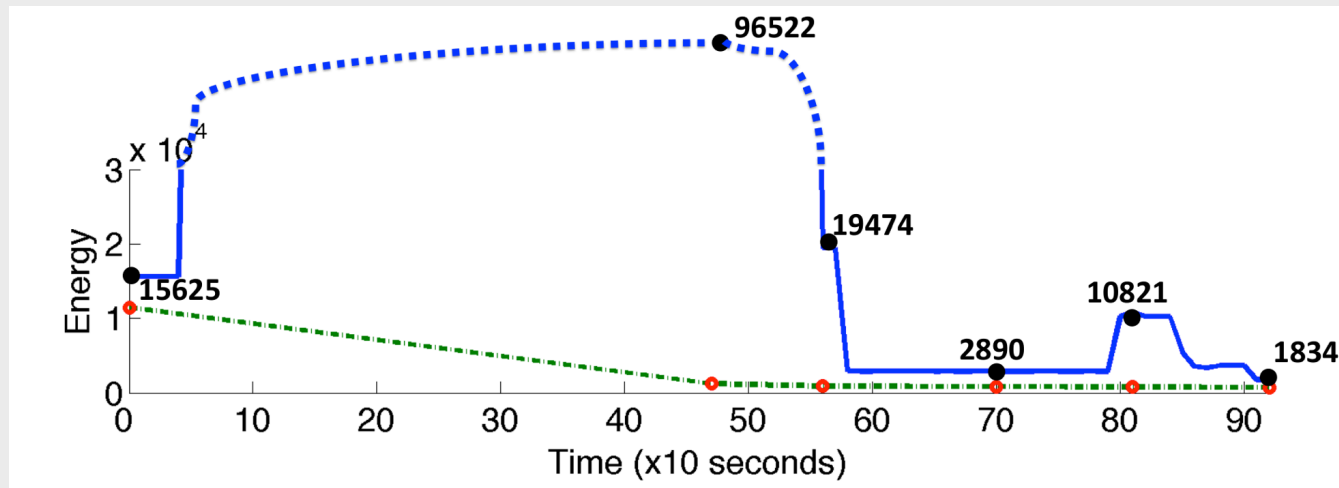


# Application 1: Refining rough compositions

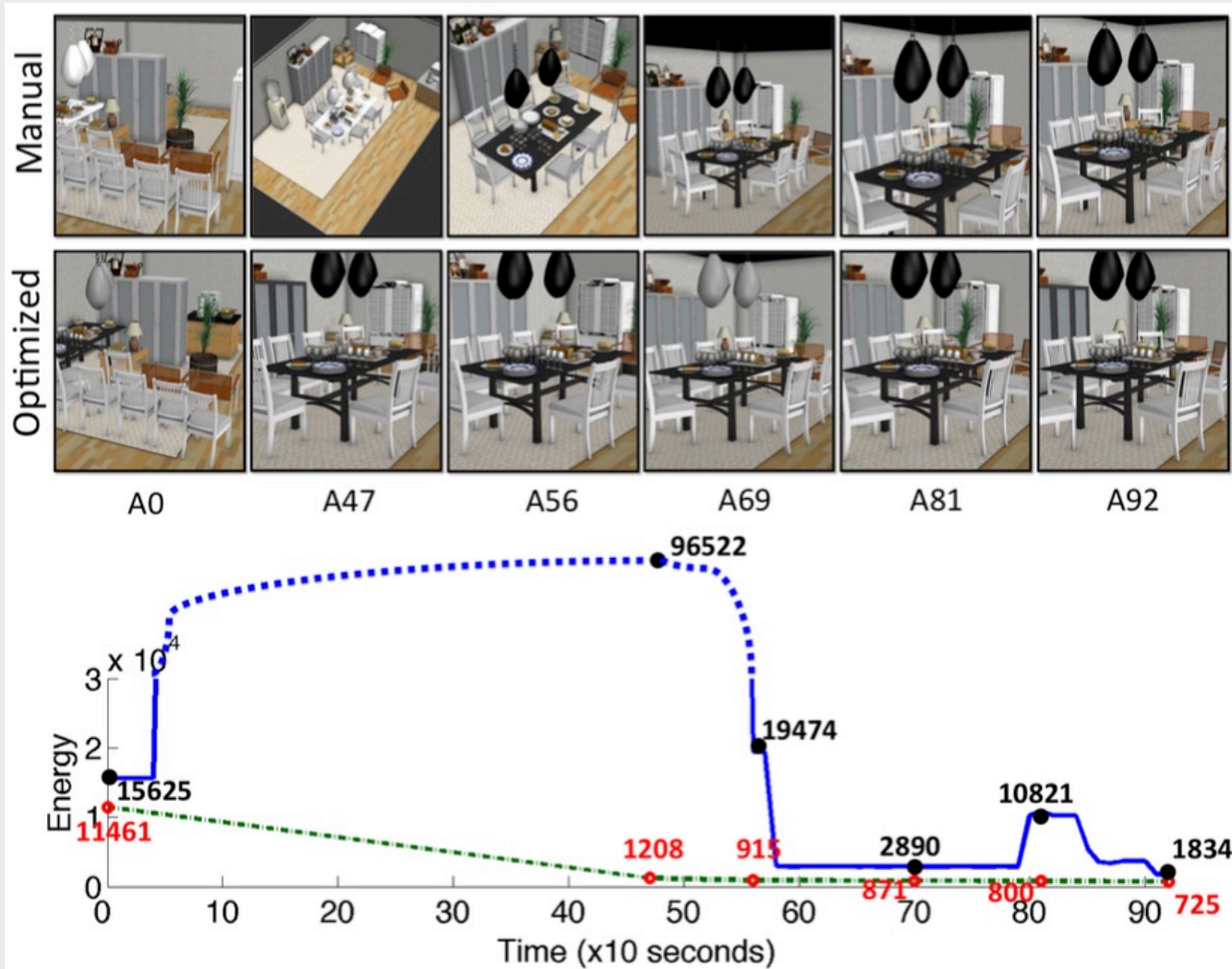




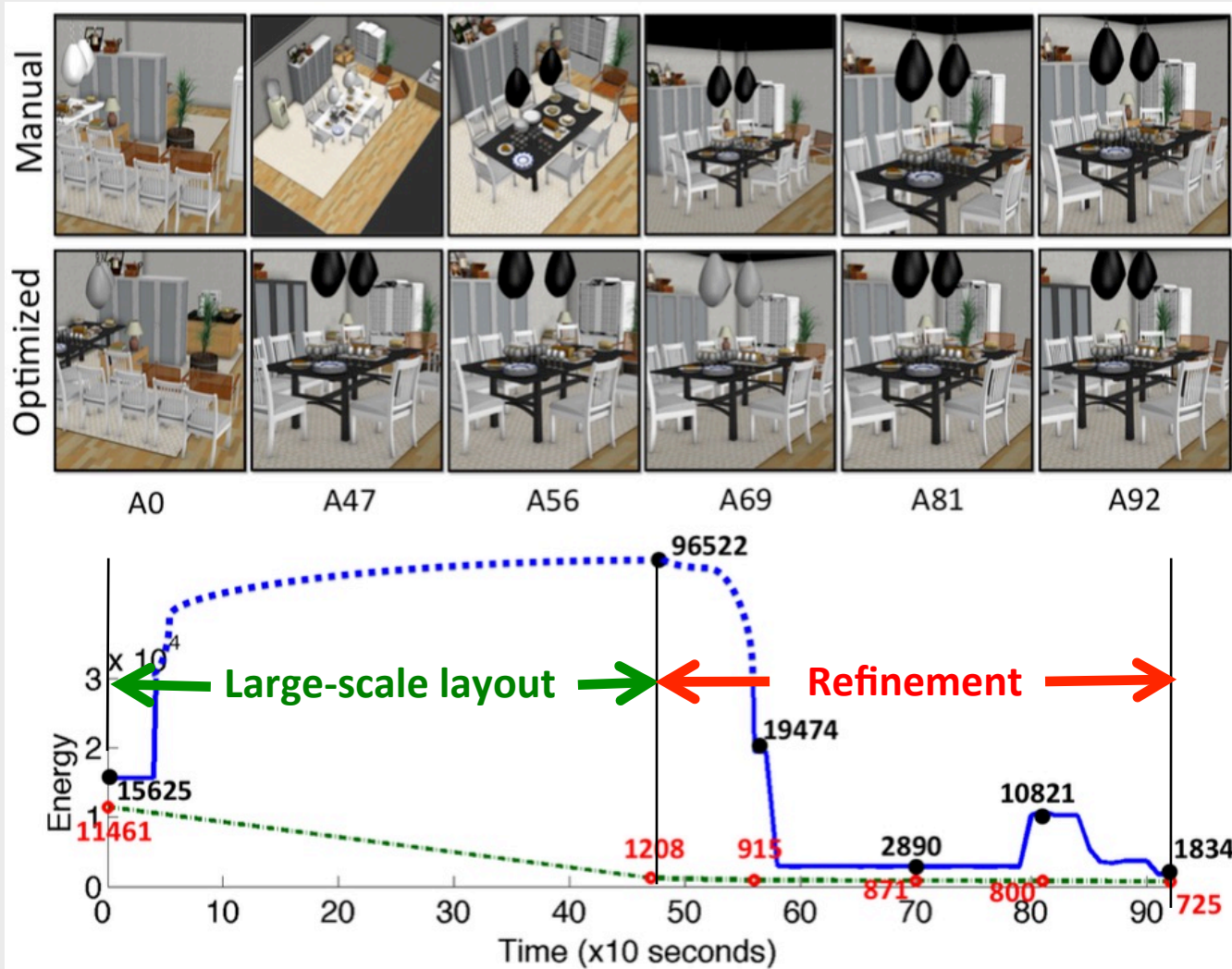
# Application 1: Refining rough compositions



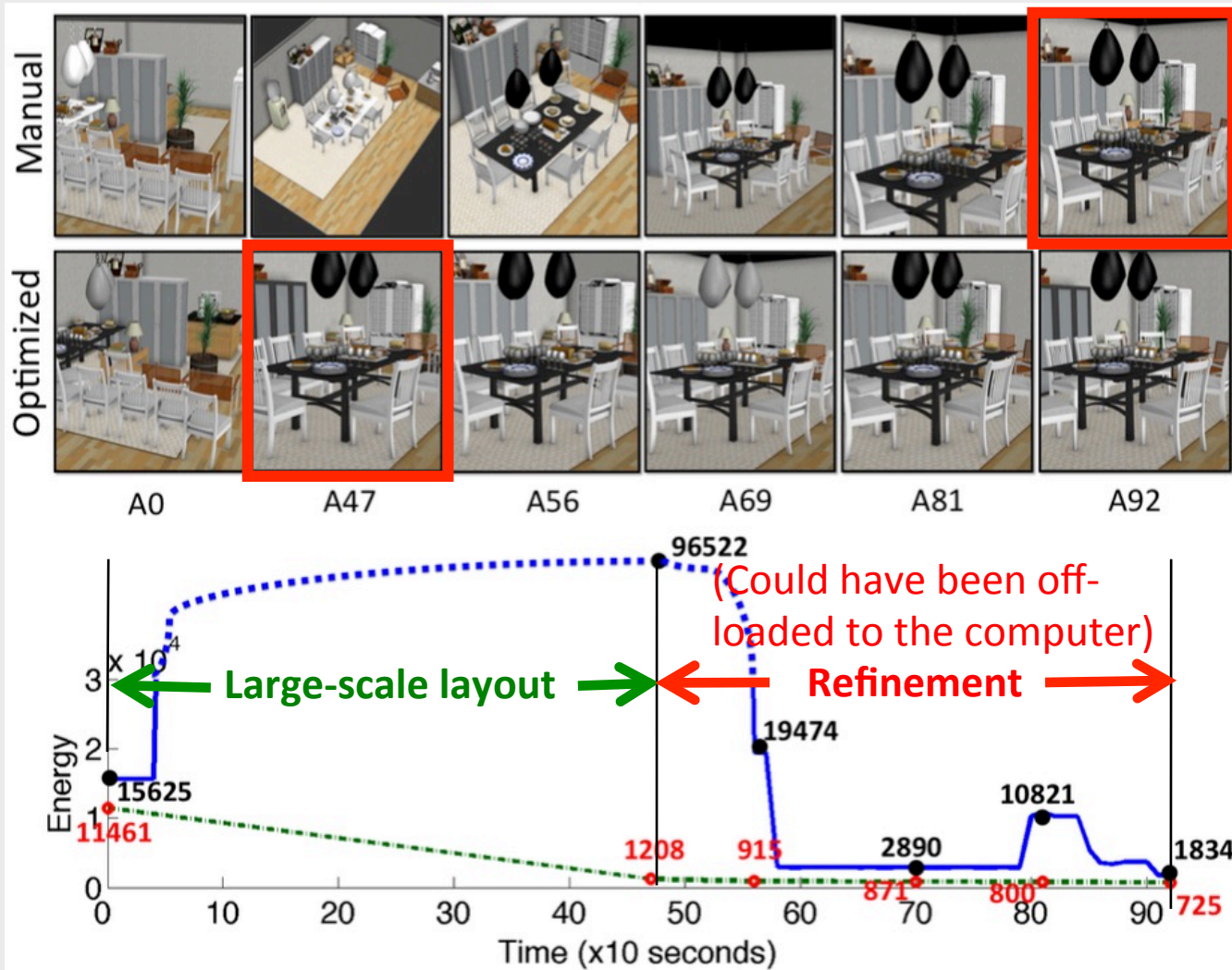
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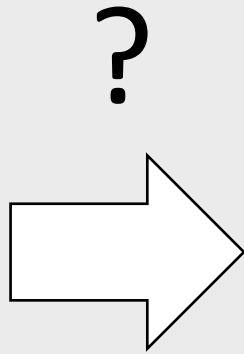
# Application 1: Refining rough compositions



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# Application 2: Retargeting for different aspect ratios



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Input (4:3)



Camera-only

# Application 2: Retargeting for different aspect ratios



Input (4:3)

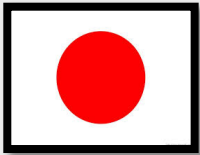


Camera-only



Ours (1:2)

# App 3: Retargeting for different cultural preferences





# App 3: Retargeting for different cultural preferences



**(a)** *Original*



**(b)** *Objects replaced*

# App 3: Retargeting for different cultural preferences



**(a)** *Original*



**(b)** *Objects replaced*



**(c)** *Optimized*

# Application 4: Text-incorporated composition



# Application 4: Text-incorporated composition



Input

# Application 4: Text-incorporated composition



Input

Extra terms for overlaid text

- Contrast term

# Application 4: Text-incorporated composition



Input

Extra terms for overlaid text

- Contrast term
- Variance term

# Application 4: Text-incorporated composition



Input



Camera only

# Application 4: Text-incorporated composition



Input



Camera only



Our result



# Application 5: Generating detail images from an overview



# Application 5: Generating detail images from an overview



# Application 5: Generating detail images from an overview



# Application 5: Generating detail images from an overview



**(a)** *Overview*

# Application 5: Generating detail images from an overview



**(a)** *Overview*



**(b)** *Speaker*

# Application 5: Generating detail images from an overview



**(a)** *Overview*



**(b)** *Speaker*



**(c)** *Shelf*

# A Perceptual Study

Comparing the results of our method and optimizing camera only.



Kitchen



Study



Living room

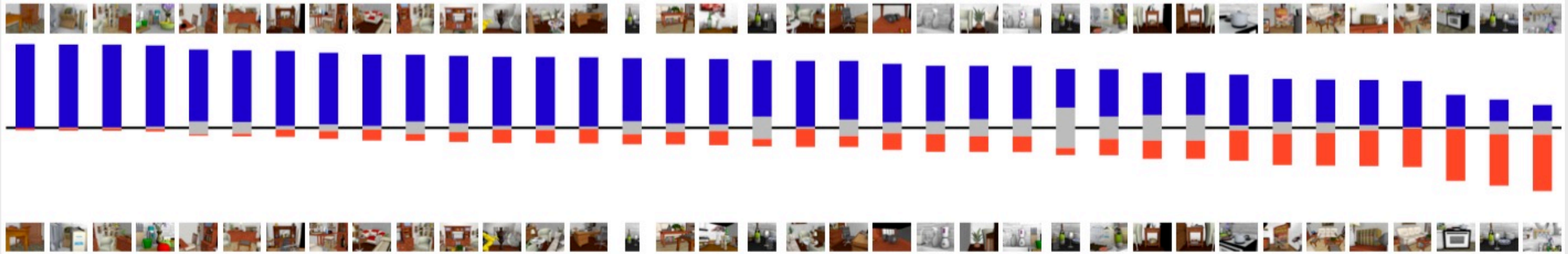
# Expert Study Results

ID	Ours	Camera Only	No preference
Expert 1	22	12	2
Expert 2	17	14	3
Expert 3	22	11	3
Expert 4	21	12	3

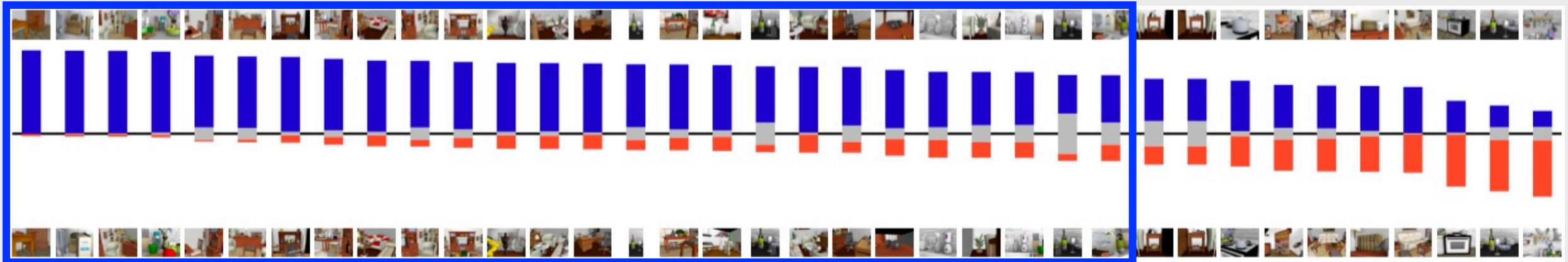




# Amazon Mechanical Turk Study

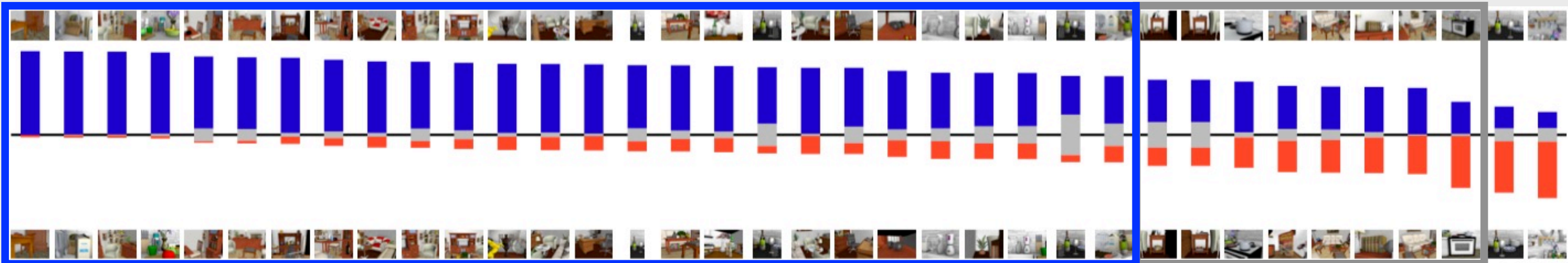


# Amazon Mechanical Turk Study



- If null hypothesis is there is no preference,
- Our method is preferred in **26/36** cases.

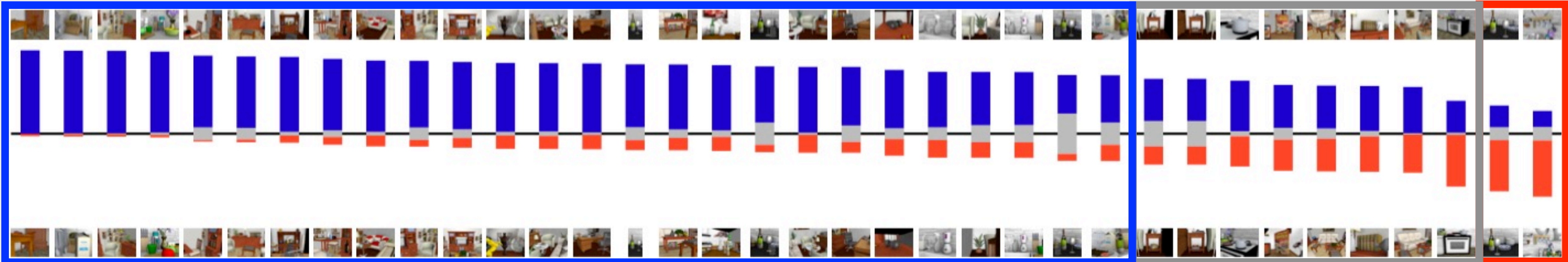
# Amazon Mechanical Turk Study



If null hypothesis is there is no preference,

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- No statistical significance in **8** cases.

# Amazon Mechanical Turk Study



If null hypothesis is there is no preference,

- Our method is preferred in **26/36** cases.
- No statistical significance in **8** cases.
- Camera only is preferred in **2** cases.



# Summary

- Moving objects and changing materials significantly improves the quality of compositions.
- Our optimization framework benefits a variety of applications.



# Limitation and future work

- Interactive scene optimization
- Global illumination
- Additional composition rules



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- Global illumination
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Symmetry



Vanishing points

# Acknowledgement

## Interviews

- Martin Enthed and Helen Crowther

## Catalogue images

- IKEA

## Funding

- NSF, Intel, Adobe



# Thank you!

## Take-away message

- Moving objects and changing materials significantly improves the quality of compositions.
- Our optimization framework benefits a variety of applications.



(a) *Overview*



(b) *Speaker*



(c) *Shelf*